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# Machine Learning

CSE 6363 (Fall 2016)

Lecture 14 Kernel PCA and Tensor

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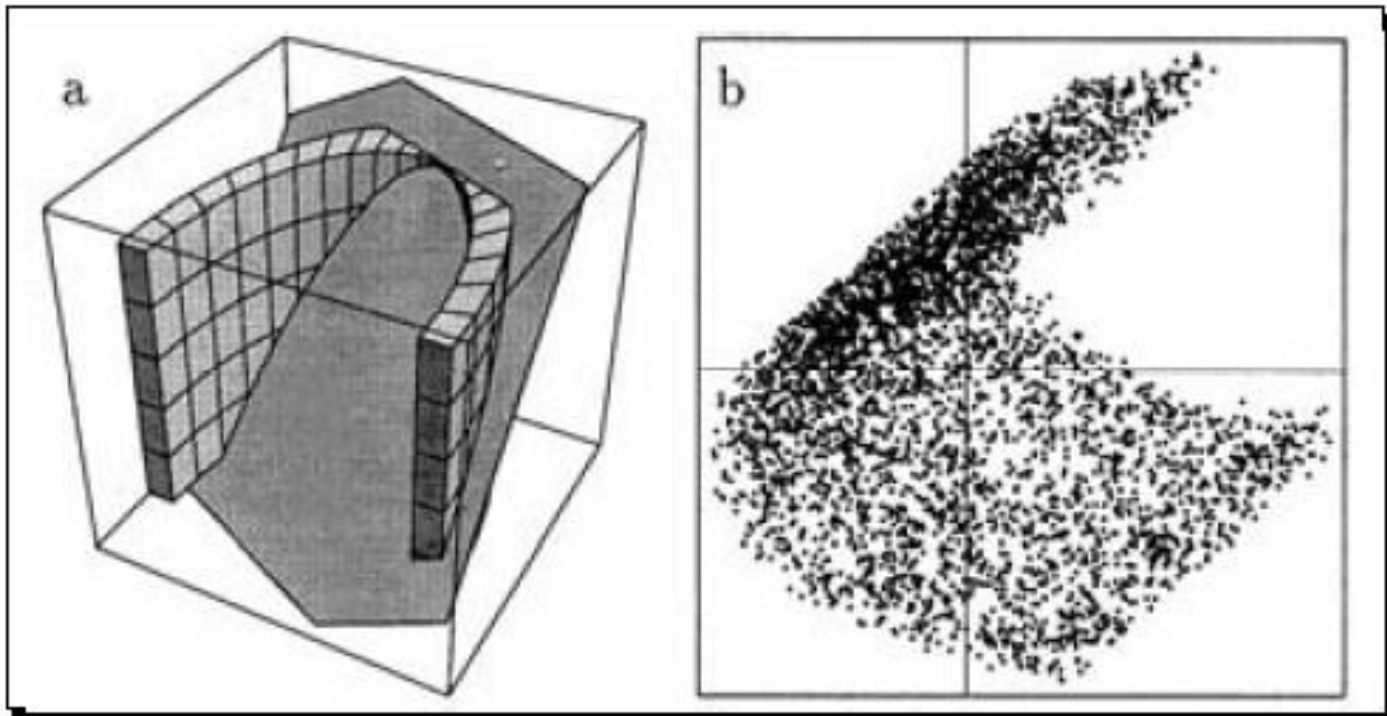
Department of Computer Science and Engineering

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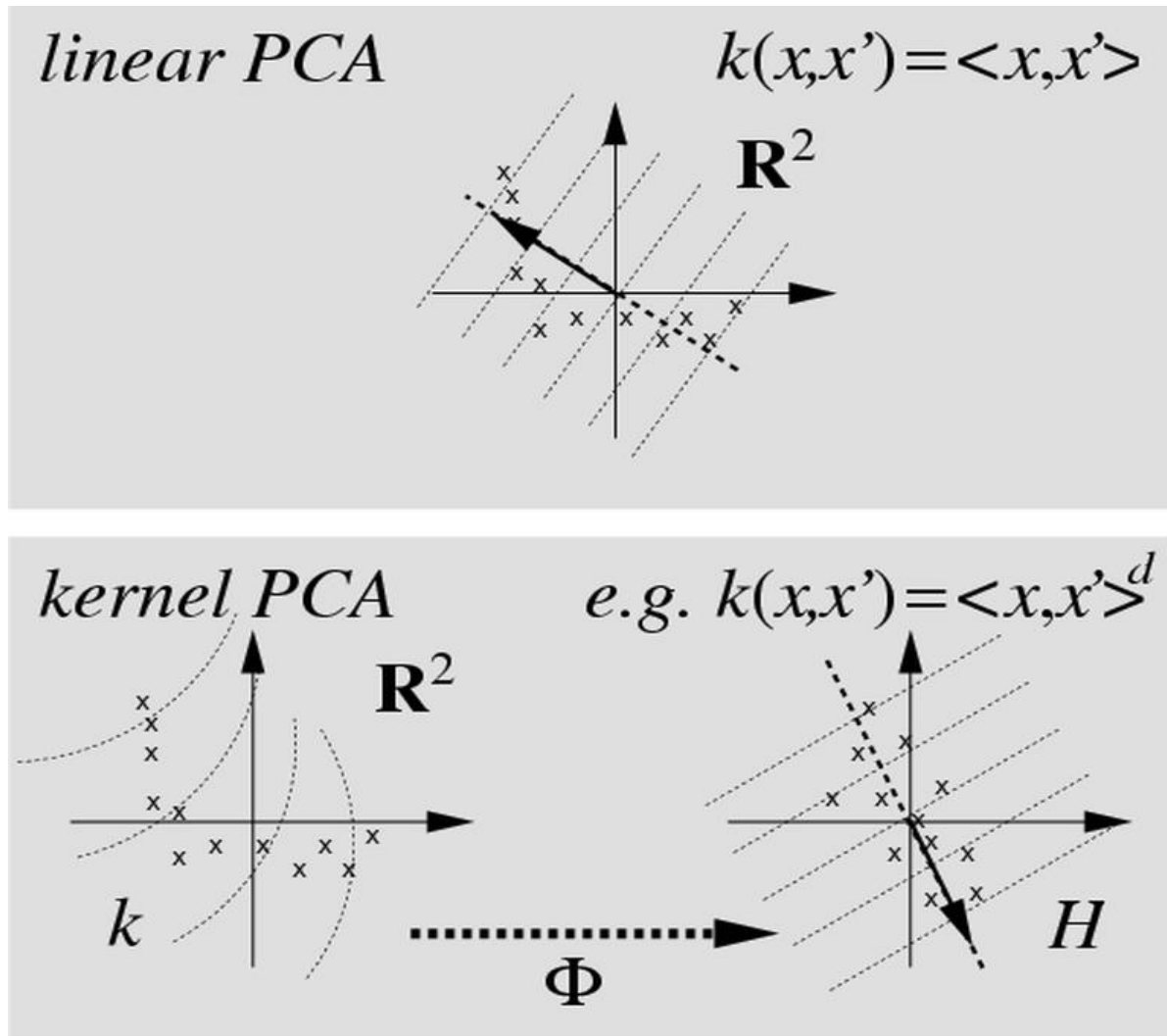
# Limitations of Linear PCA

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$$\lambda_{1,2,3}=1/3$$



# Kernel PCA: The Main Idea



# PCA Revisit

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Sample covariance matrix:

$$C = \frac{1}{N} \sum_i \mathbf{x}_i \mathbf{x}_i^T$$

Linear PCA:

$$U \Lambda U^T = C \quad \Rightarrow \quad C = \sum_a \lambda_a \mathbf{u}_a \mathbf{u}_a^T$$

The projection is given by:

$$\mathbf{y}_i = U_k^T \mathbf{x}_i \quad \forall i$$

The projected data are de-correlated:

$$\frac{1}{N} \sum_i \mathbf{y}_i \mathbf{y}_i^T = \frac{1}{N} \sum_i U_k^T \mathbf{x}_i \mathbf{x}_i^T U_k = U_k^T C U_k = U_k^T U \Lambda U^T U_k = \Lambda_k$$

Different point of view of PCA:  $\sum_i \|\mathbf{x}_i - \mathcal{P}_k \mathbf{x}_i\|^2$

# Kernel Method in PCA

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The eigen-vectors that span the projection space must lie in the subspace spanned by the data-cases:

$$\begin{aligned}\lambda_a \mathbf{u}_a &= C \mathbf{u}_a = \frac{1}{N} \sum_i \mathbf{x}_i \mathbf{x}_i^T \mathbf{u}_a = \frac{1}{N} \sum_i (\mathbf{x}_i^T \mathbf{u}_a) \mathbf{x}_i \\ \Rightarrow \mathbf{u}_a &= \sum_i \frac{(\mathbf{x}_i^T \mathbf{u}_a)}{N \lambda_a} \mathbf{x}_i = \sum_i \alpha_i^a \mathbf{x}_i\end{aligned}$$

PCA eigenvalue function:  $C \mathbf{u} = \lambda \mathbf{u}$

$N$  equations as:

$$\begin{aligned}\mathbf{x}_i^T C \mathbf{u}_a &= \lambda_a \mathbf{x}_i^T \mathbf{u}_a \Rightarrow \\ \mathbf{x}_i^T \frac{1}{N} \sum_k \mathbf{x}_k \mathbf{x}_k^T \sum_j \alpha_j^a \mathbf{x}_j &= \lambda_a \mathbf{x}_i^T \sum_j \alpha_j^a \mathbf{x}_j \Rightarrow \\ \frac{1}{N} \sum_{j,k} \alpha_j^a [\mathbf{x}_i^T \mathbf{x}_k] [\mathbf{x}_k^T \mathbf{x}_j] &= \lambda_a \sum_j \alpha_j^a [\mathbf{x}_i^T \mathbf{x}_j]\end{aligned}$$

# Kernel Method in PCA

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Define the matrix  $[\mathbf{x}_i^T \mathbf{x}_j] = K_{ij}$

$$\begin{aligned} K^2 \boldsymbol{\alpha}^a &= N \lambda_a K \boldsymbol{\alpha}^a \\ \Rightarrow K \boldsymbol{\alpha}^a &= (\tilde{\lambda}_a) \boldsymbol{\alpha}^a & \tilde{\lambda}_a &= N \lambda_a \end{aligned}$$

Orthonormal constraint:

$$\begin{aligned} \mathbf{u}_a^T \mathbf{u}_a &= 1 \\ \Rightarrow \sum_{i,j} \alpha_i^a \alpha_j^a [\mathbf{x}_i^T \mathbf{x}_j] &= \boldsymbol{\alpha}_a^T K \boldsymbol{\alpha}_a = N \lambda_a \boldsymbol{\alpha}_a^T \boldsymbol{\alpha}_a = 1 \\ \Rightarrow \|\boldsymbol{\alpha}_a\| &= 1/\sqrt{N \lambda_a} \end{aligned}$$

Kernel PCA projection:

$$\mathbf{u}_a^T \mathbf{t} = \sum_i \alpha_i^a \mathbf{x}_i^T \mathbf{t} = \sum_i \alpha_i^a K(\mathbf{x}_i, \mathbf{t})$$

# Center Kernel PCA

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It is difficult to center the data in feature space. But we can center kernel matrix.

$$K_{ij} = \Phi_i \Phi_j^T$$

$$\Phi_i = \Phi_i - \frac{1}{N} \sum_k \Phi_k$$

$$\begin{aligned} K_{ij}^c &= (\Phi_i - \frac{1}{N} \sum_k \Phi_k)(\Phi_j - \frac{1}{N} \sum_l \Phi_l)^T \\ &= \Phi_i \Phi_j^T - [\frac{1}{N} \sum_k \Phi_k] \Phi_j^T - \Phi_i [\frac{1}{N} \sum_l \Phi_l^T] + [\frac{1}{N} \sum_k \Phi_k][\frac{1}{N} \sum_l \Phi_l^T] \\ &= K_{ij} - \kappa_i \mathbf{1}_j^T - \mathbf{1}_i \kappa_j^T + k \mathbf{1}_i \mathbf{1}_j^T \end{aligned}$$

$$\kappa_i = \frac{1}{N} \sum_k K_{ik}$$

$$k = \frac{1}{N^2} \sum_{ij} K_{ij}$$

# Center Kernel PCA

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At test-time, we need compute:

$$K_c(\mathbf{t}_i, \mathbf{x}_j) = \left[ \Phi(\mathbf{t}_i) - \frac{1}{N} \sum_k \Phi(\mathbf{x}_k) \right] \left[ \Phi(\mathbf{x}_j) - \frac{1}{N} \sum_l \Phi(\mathbf{x}_l) \right]^T$$

Similar to the derivations in last slide, we have:

$$K_c(\mathbf{t}_i, \mathbf{x}_j) = K(\mathbf{t}_i, \mathbf{x}_j) - \boldsymbol{\kappa}(\mathbf{t}_i) \mathbf{1}_j^T - \mathbf{1}_i \boldsymbol{\kappa}(\mathbf{x}_j)^T + k \mathbf{1}_i \mathbf{1}_j^T$$



# Algorithm

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Input: Data  $\mathbf{X} = \{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_l\}$  in  $n$ -dimensional space.

Process:  $\mathbf{K}_{i,j} = k(\mathbf{x}_i, \mathbf{x}_j); \quad i, j = 1, \dots, l.$                       Kernel matrix ...

$$\hat{\mathbf{K}} = \mathbf{K} - \frac{1}{l} \mathbf{j} \cdot \mathbf{j}' \cdot \mathbf{K} - \frac{1}{l} \mathbf{K} \cdot \mathbf{j} \cdot \mathbf{j}' + \frac{1}{l^2} (\mathbf{j}' \cdot \mathbf{K} \cdot \mathbf{j}) \cdot \mathbf{j} \cdot \mathbf{j}'; \quad \dots \text{ for centered data}$$

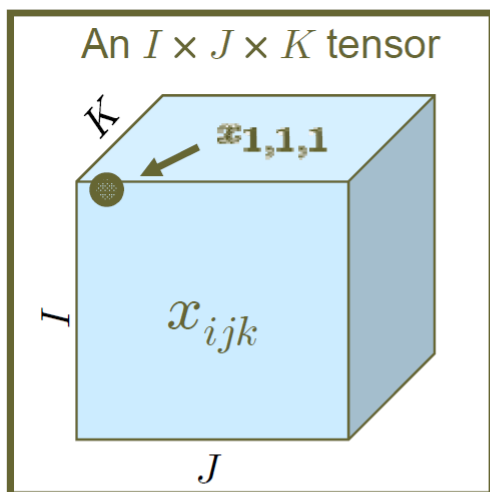
$$[\mathbf{W}, \Lambda] = \text{eig}(\hat{\mathbf{K}});$$

$$\alpha^{(j)} = \frac{1}{\sqrt{\lambda_j}} \mathbf{w}_j, \quad j = 1, \dots, l.$$

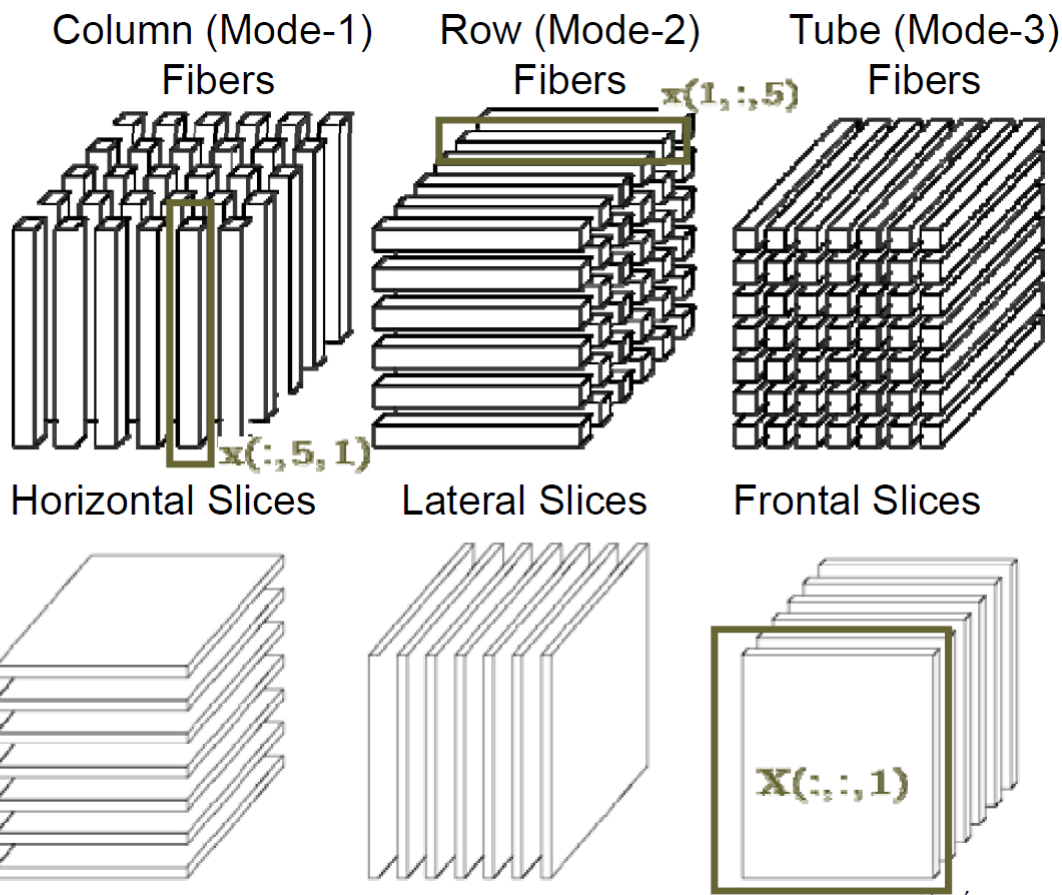
$$\tilde{\mathbf{x}}_j = \left( \sum_{i=1}^l \alpha_i^{(j)} k(\mathbf{x}_i, \mathbf{x}) \right)_{j=1}^k \quad \text{\textit{k}-dimensional vector projection of new data into this subspace}$$

Output: Transformed data

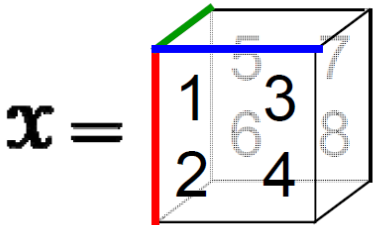
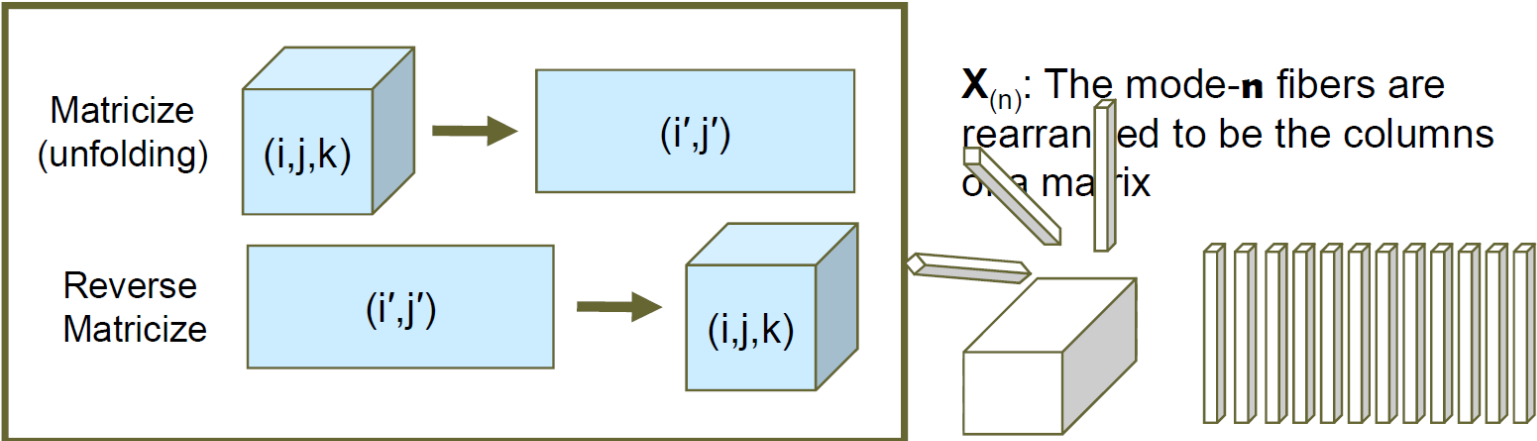
# A Tensor Is A Multidimensional Array



3<sup>rd</sup> order tensor  
 mode 1 has dimension  $I$   
 mode 2 has dimension  $J$   
 mode 3 has dimension  $K$



# Matricization : Converting Tensor to Matrix



$$\mathbf{X}_{(1)} = \begin{bmatrix} 1 & 3 & 5 & 7 \\ 2 & 4 & 6 & 8 \end{bmatrix}$$

$$\mathbf{X}_{(2)} = \begin{bmatrix} 1 & 2 & 5 & 6 \\ 3 & 4 & 7 & 8 \end{bmatrix}$$

$$\mathbf{X}_{(3)} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \end{bmatrix}$$

$\mathbf{X}$        $\mathbf{X}_{(3)}$

Vectorization

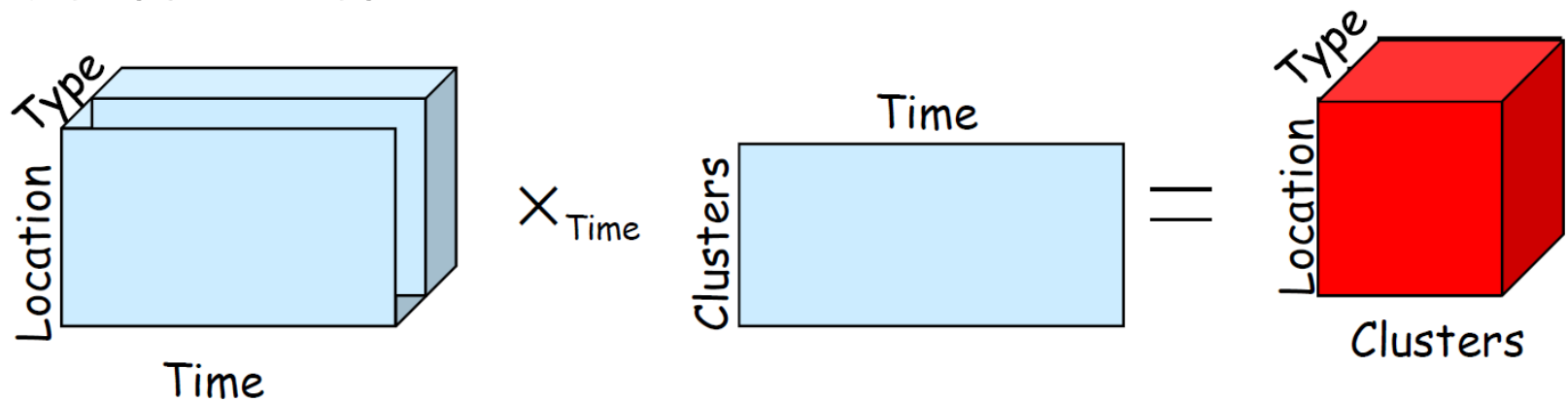
$$\text{vec}(\mathbf{X}) = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \\ 7 \\ 8 \end{bmatrix}$$

3-4

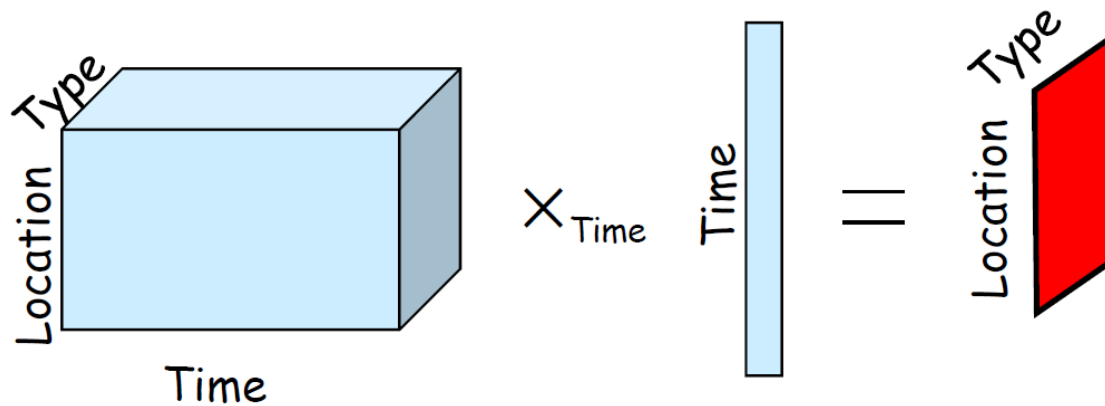
# Mode-n Product Example

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Tensor times a matrix



Tensor times a vector

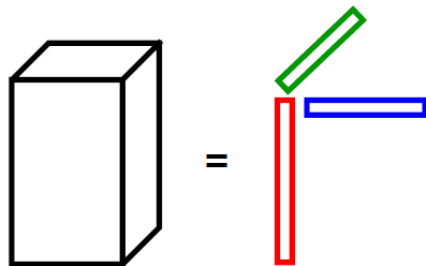


# Outer, Kronecker, & Khatri-Rao Products

3-Way Outer Product

$$\mathbf{X} = \mathbf{a} \circ \mathbf{b} \circ \mathbf{c}$$

$$x_{ijk} = a_i b_j c_k$$



Rank-1 Tensor

Review: Matrix Kronecker Product

$$\mathbf{A} \otimes \mathbf{B} = \begin{bmatrix} a_{11}\mathbf{B} & a_{12}\mathbf{B} & \cdots & a_{1N}\mathbf{B} \\ a_{21}\mathbf{B} & a_{22}\mathbf{B} & \cdots & a_{2N}\mathbf{B} \\ \vdots & \vdots & \ddots & \vdots \\ a_{M1}\mathbf{B} & a_{M2}\mathbf{B} & \cdots & a_{MN}\mathbf{B} \end{bmatrix}$$

$M \times N$     $P \times Q$     $MP \times NQ$

$$= \begin{bmatrix} \mathbf{a}_1 \otimes \mathbf{b}_1 & \mathbf{a}_1 \otimes \mathbf{b}_2 & \cdots & \mathbf{a}_N \otimes \mathbf{b}_Q \end{bmatrix}$$

Matrix Khatri-Rao Product

$$\mathbf{A} \odot \mathbf{B} = \begin{bmatrix} \mathbf{a}_1 \otimes \mathbf{b}_1 & \mathbf{a}_2 \otimes \mathbf{b}_2 & \cdots & \mathbf{a}_R \otimes \mathbf{b}_R \end{bmatrix}$$

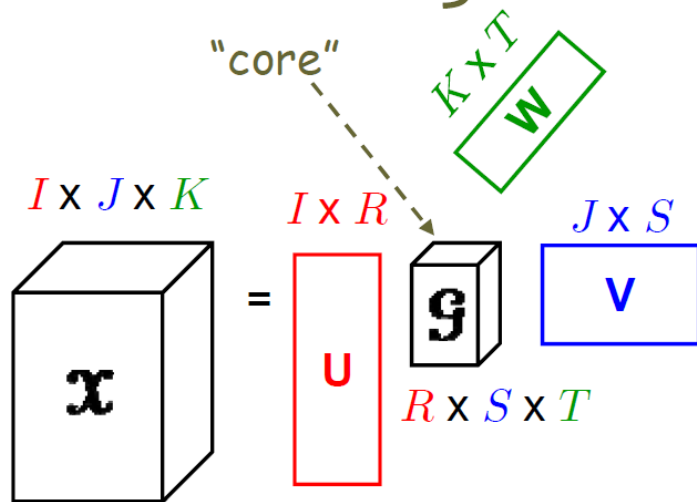
$M \times R$     $N \times R$     $MN \times R$

Observe: For two vectors  $\mathbf{a}$  and  $\mathbf{b}$ ,  $\mathbf{a} \circ \mathbf{b}$  and  $\mathbf{a} \otimes \mathbf{b}$  have the same elements, but one is shaped into a matrix and the other into a vector.

# Specially Structured Tensors

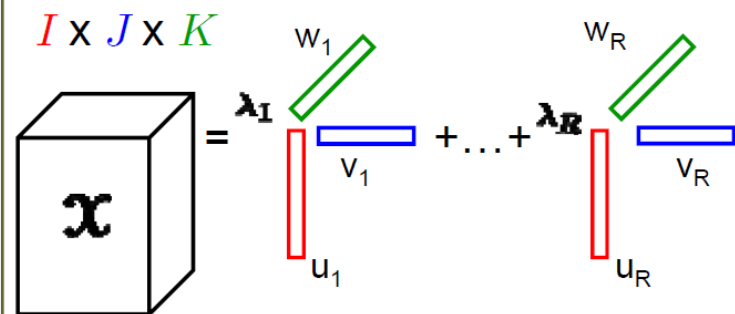
- Tucker Tensor

$$\begin{aligned} \mathbf{X} &= \mathbf{G} \times_1 \mathbf{U} \times_2 \mathbf{V} \times_3 \mathbf{W} \\ &= \sum_r \sum_s \sum_t g_{rst} \mathbf{u}_r \circ \mathbf{v}_s \circ \mathbf{w}_t \\ &\equiv [\mathbf{G}; \mathbf{U}, \mathbf{V}, \mathbf{W}] \end{aligned} \left. \vphantom{\sum_r \sum_s \sum_t} \right\} \text{Our Notation}$$



- Kruskal Tensor

$$\begin{aligned} \mathbf{X} &= \sum_r \lambda_r \mathbf{u}_r \circ \mathbf{v}_r \circ \mathbf{w}_r \\ &\equiv [\boldsymbol{\lambda}; \mathbf{U}, \mathbf{V}, \mathbf{W}] \end{aligned} \left. \vphantom{\sum_r} \right\} \text{Our Notation}$$



# What Is The HO Analogue of The Matrix SVD?

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Matrix SVD:

$$\mathbf{X} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^T = \begin{array}{c} \color{red}\blacksquare \\ \color{black}\square \\ \color{blue}\blacksquare \end{array} = \sigma_1 \begin{array}{c} \color{red}\boxed{\phantom{0}} \\ \color{blue}\boxed{\phantom{0}} \end{array} + \sigma_2 \begin{array}{c} \color{red}\boxed{\phantom{0}} \\ \color{blue}\boxed{\phantom{0}} \end{array} + \dots + \sigma_R \begin{array}{c} \color{red}\boxed{\phantom{0}} \\ \color{blue}\boxed{\phantom{0}} \end{array}$$

Tucker Tensor (finding bases for each subspace):

$$\mathbf{X} = \mathbf{\Sigma} \times_1 \mathbf{U} \times_2 \mathbf{V} = [[\mathbf{\Sigma} ; \mathbf{U}, \mathbf{V}]]$$

Kruskal Tensor (sum of rank-1 components):

$$\mathbf{X} = \sum_{r=1}^R \sigma_r \mathbf{u}_r \circ \mathbf{v}_r = [[\boldsymbol{\sigma} ; \mathbf{U}, \mathbf{V}]]$$

# SVD and 2D-SVD

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SVD

$$X = (x_1, x_2, \dots, x_n)$$

Eigenvectors of  $XX^T$  and  $X^T X$

$$X = U\Sigma V^T \quad \Sigma = U^T X V$$

2D-SVD

$$\{A\} = \{A_1, A_2, \dots, A_n\}$$

Eigenvectors of

$$F = \sum_i (A_i - \bar{A})(A_i - \bar{A})^T \quad \text{row-row covariance}$$

$$G = \sum_i (A_i - \bar{A})^T (A_i - \bar{A}) \quad \text{column-column cov}$$

$$A_i = U M_i V^T \quad M_i = U^T A_i V$$



# 2D-SVD

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$$\{A\} = \{A_1, A_2, \dots, A_n\} \quad \text{assume } \bar{A} = 0$$

row-row cov:  $F = \sum_i A_i A_i^T = \sum \lambda_k u_k u_k^T$

col-col cov:  $G = \sum_i A_i^T A_i = \sum_{k=1} \zeta_k u_k u_k^T$

Bilinear  $U = (u_1, u_2, \dots, u_k)$

subspace  $V = (v_1, v_2, \dots, v_k) \quad M_i = U^T A_i V$

$$A_i = U M_i V^T, i = 1, \dots, n$$

$$A_i \in \mathfrak{R}^{r \times c}, U \in \mathfrak{R}^{r \times k}, V \in \mathfrak{R}^{c \times k}, M_i \in \mathfrak{R}^{k \times k}$$