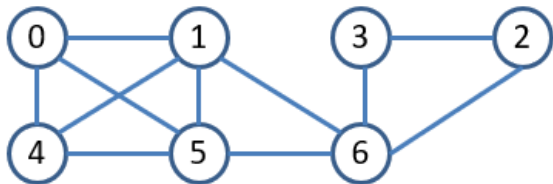


BFS-Visit(G,s) // search graph G starting from vertex s .

1. For each vertex u of G
 1. $color[u] = WHITE$ // undiscovered
 2. $dist[u] = inf$ // distance from s to u
 3. $pred[u] = NIL$ // predecessor of u on the path from s to u
2. $color[s] = GRAY$ // s is being processed
3. $dist[s] = 0$
4. $pred[s] = NIL$
5. Initialize empty queue Q
6. $put(Q,s)$ // s goes to the end of Q
7. While Q is not empty
 1. $u = get(Q)$ // removes u from the front of Q
 2. For each v adjacent to u // explore edge (u,v) // in increasing order
 1. If $color[v] == WHITE$
 1. $color[v] = GRAY$
 2. $dist[v] = dist[u]+1$
 3. $pred[v] = u$
 4. $put(Q,v)$
 3. $color[u] = BLACK$

Representation	BFS time complexity	BFS space complexity
Adj LIST	$O(\underline{\hspace{2cm}})$	
Adj MATRIX	$O(\underline{\hspace{2cm}})$	



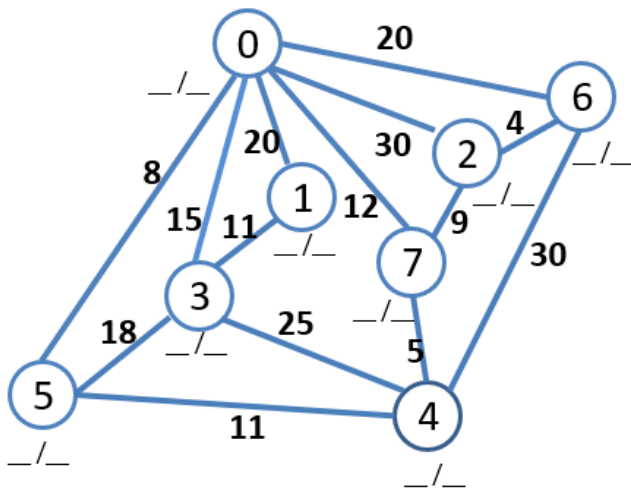
Vertex	0	1	2	3	4	5	6
Work (dist and parent updates for nodes)							

```

MST_Prim(G,w,s) // N = |V|
1  int d[N], p[N]
2  For v =0 -> N-1
3    d[v]=inf //min weight of edge connecting v to MST
4    p[v]=-1 //MST vertex, s.t. w(p[v],v) =d[v]
5  d[s]=0
6  Q = PriorityQueue(G.V, d)
7  While notEmpty(Q)
8    u = removeMin(Q,d)
9    for each v adjacent to u
10     if v in Q and w(u,v)<d[v] {
11       p[v]=u
12       d[v] = w(u,v);
13       decreasedKeyFix(Q,v,d) //v is neither index nor key
14     }
15 }

```

Assume adjacency list representation. TC: SC:



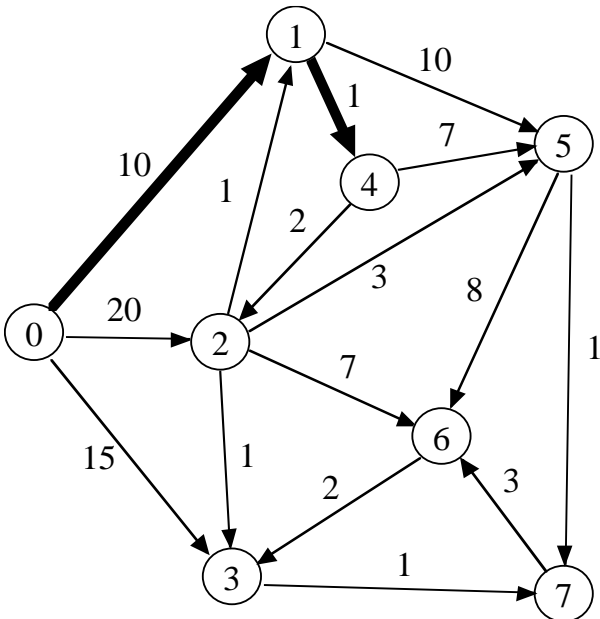
Vertex	0	1	2	3	4	5	6	7
Work (dist and parent updates for nodes)								

Dijkstra(G,w,s) // N = |V|

```

1  int d[N], p[N]
2  For v = 0 -> N-1
3    d[v]=inf //total weight from s to v
4    p[v]=-1 //v's predecessor on path s to v
5  d[s]=0
6  Q = PriorityQueue(d)
7  While notEmpty(Q) {
8    u = removeMin(Q,w)
9    for each v adjacent to u
10     if v in Q and (d[u]+w(u,v))<d[v]{
11       p[v]=u
12       d[v] = d[u]+w(u,v);
13       decreasedKeyFix(Q,v,d)
14     }
15 }

```



Vertex	0	1	2	3	4	5	6	7
Work (dist and parent updates for nodes)								