

Homework Set 2

Exercise 9.2

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Online Computation And Competitive Analysis Borodin & El-Yaniv

Statement of Exercise

Given an N -state MTS, an initial state, and a task sequence of length n , what are the time and space complexities to compute the optimal off-line schedule and cost to serve the task sequence using the [above] work function method?

Short Answer

*The time and space complexities of generation and traceback of the **dynamic programming table** for offline-WFA.*

Task Type Processing Cost

In general:

- Single task of given *type* could incur a different processing cost in each of N MTS states.
- $\mathbf{T} = \{\text{task types}\}: |\mathbf{T}| = T \leq N$.
- *Represent as a function:*

$$tpc : (\mathbf{T} \times \mathbf{N}) \rightarrow \mathbb{R}^+ \quad (0 \notin \mathbb{R}^+)$$

- $|\mathit{tpc}| = |\mathbf{T}| \cdot |\mathbf{V}| = T \cdot N \leq N \cdot N = N^2$

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Task Type Processing Cost

“TPC” Table: $Storage = |\mathbf{T}| \cdot |\mathbf{V}| = \mathbf{T} \cdot \mathbf{N} \leq \mathbf{N}^2$

		<i>MTS State</i>						
		1	2	3	...	s	...	N
<i>Task Type</i>	1	$r(1,1)$	$r(1,2)$	$r(1,3)$	•	$r(1,s)$	•	$r(1,N)$
	2	$r(2,1)$	$r(2,2)$	$r(2,3)$	•	$r(2,s)$	•	$r(2,N)$
•	•	•	•	•	•	•	•	
<i>t</i>	$r(t,1)$	$r(t,2)$	$r(t,3)$	•	$r(t,s)$	•	$r(t,N)$	
•	•	•	•	•	•	•	•	
<i>T</i>	$r(T,1)$	$r(T,2)$	$r(T,3)$	•	$r(T,s)$	•	$r(T,N)$	

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Inter-state Transition Cost

Define “*measurable (point-) space*”:

[“space (of vertices/points) is *measurable*”] \rightarrow [\exists a “*measurement function d*” that assigns a numeric value (signed magnitude of uniform units) to every vertex pair.]

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Inter-Transition Cost

In a general “measurable space”:

- Measure function is *not* necessarily symmetric:

$$(\exists x)(\exists y)[d(x,y) \neq d(y,x)], x,y \in V$$

- Such a “measurable space” is characterized as a “**non metric**-space”, and
- $|d| = |V| \cdot |V| = N \cdot N$

ITC: Non Metric-Space

“ITC” (d) Table: Storage = $|V| \cdot |V| = N \cdot N = N^2$

Inter-state Transition Cost (MTS Space NOT a Metric Space)

<i>MTS State</i>	<i>MTS State</i>						
	1	2	3	...	s	...	N
1	$d(1,1)$	$d(1,2)$	$d(1,3)$	●	$d(1,s)$	●	$d(1,N)$
2	$d(2,1)$	$d(2,2)$	$d(2,3)$	●	$d(2,s)$	●	$d(2,N)$
●	●	●	●	●	●	●	●
s	$d(s,1)$	$d(s,2)$	$d(s,3)$	●	$d(s,s)$	●	$d(s,N)$
●	●	●	●	●	●	●	●
N	$d(N,1)$	$d(N,2)$	$d(N,3)$	●	$d(N,s)$	●	$d(N,N)$

Inter-Transition Cost

But if the measure function **IS** *symmetric* -

$$(\forall x)(\forall y)[d(x,y) = d(y,x)], x,y \in \mathbf{V}:$$

Such a “*measurable space*” is characterized as a “*metric space*”, and

$$|d| = \frac{N(N+1)}{2} = \left(\frac{N}{2} + 1\right)N$$

ITC: Metric-Space

“ITC” (*d*) Table: $Storage = \frac{N(N+1)}{2}$

Inter-state Transition Cost (MTS Space IS a Metric Space)

<i>MTS State</i>	<i>MTS State</i>						
	1	2	3	...	s	...	N
1	<i>d</i> (1,1)	<i>d</i> (1,2)	<i>d</i> (1,3)	●	<i>d</i> (1,s)	●	<i>d</i> (1,N)
2		<i>d</i> (2,2)	<i>d</i> (2,3)	●	<i>d</i> (2,s)	●	<i>d</i> (2,N)
●			●	●	●	●	●
s					<i>d</i> (s,s)	●	<i>d</i> (s,N)
●						●	●
N							<i>d</i> (N,N)

ITC: Metric-Space

Important comments:

- Foregoing explicitly includes:
$$(\forall x)[d(x,x)], x \in \mathbf{V}$$
- No explicit claim made concerning value of any such member.
- Guarantee that Triangle Inequality does not fail is enforced if $(\forall x)[d(x,x) = 0], x \in \mathbf{V}$ **and at risk otherwise.**
- Algorithmic-time-wise, “cost” of lookup returning 0 traded for cost of compare $(x = x)$ computing 0.

Offline-WFA-computation DP Table

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MTS State							
	1	...	j	...	s	...	N
	$w_0(1) = d(s_0, 1)$...	$w_0(j) = d(s_0, j)$...	$w_0(s) = d(s_0, s)$...	$w_0(N) = d(s_0, N)$

Task (Request) Sequence	r_1	$w_1(1)$	x	...	$w_1(j)$	x	...	$w_1(s)$	x	...	$w_1(N)$	x
	r_{i-1}	$w_{i-1}(1)$	x	...	$w_{i-1}(j)$	x	...	$w_{i-1}(s)$	x	...	$w_{i-1}(N)$	x
	r_i	$w_i(1)$	x	...	$w_i(j)$	x	...	$w_i(s)$	x	...	$w_i(N)$	x
	r_n	$w_n(1)$	x	...	$w_n(j)$	x	...	$w_n(s)$	x	...	$w_n(N)$	x

$r_i(x) = tpc(t_r, x)$

$w_i(s) \quad x$

$w_i(s) = \min_{x \in S} [w_{i-1}(x) + r_i(x) + d(x, s)]$

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Offline-WFA-computation DP Table

Storage Requirements:

- $\text{Length}(\sigma) = n$
- $|\mathbf{V}| = N$
- “ $w_i(s)|_x$ ” & x : 2 storage items

Total storage for this table:

$2nN$

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Toward Total Storage Requirement

- Task Type Processing Cost Table:

$$|t_{tpc}| = T \cdot N (\leq N^2)$$

- Inter-state Transition Cost Table:

$$|d|_{not\ metric} = N \cdot N$$

$$|d|_{metric} = \frac{N(N+1)}{2} = \left(\frac{N}{2} + 1\right)N$$

- Offline-WFA-Computation DP Table:

$$2nN$$

Storage Requirement: Not-metric Space

Total storage = $|t_{tpc}| + |d| + |DP\ Table|$:

$$Actual = TN + NN + 2nN$$

$$= 1 \cdot N^2 + (2n + T)N$$

$$Limit_{T=N} = NN + NN + 2nN$$

$$= 2 \cdot N^2 + (2n)N$$

$$= Actual + (N - T)N$$

Storage Requirement: Metric Space

Total storage = $|t\text{tpc}| + |d| + |\text{DP Table}|$:

$$\text{Actual} = TN + N \left(\frac{N}{2} + 1 \right) + 2nN = \frac{N^2}{2} + TN + N + 2nN$$

$$= \left(\frac{1}{2} \right) N^2 + (2n + 1 + T) N$$

$$\text{Limit} = \frac{N^2}{2} + N^2 + N + 2nN = \left(\frac{1}{2} + 1 \right) N^2 + (2n + 1) N$$

$$= \text{Actual} + (N - T) N$$

Storage Requirement Recap

Storage requirements then are of the form

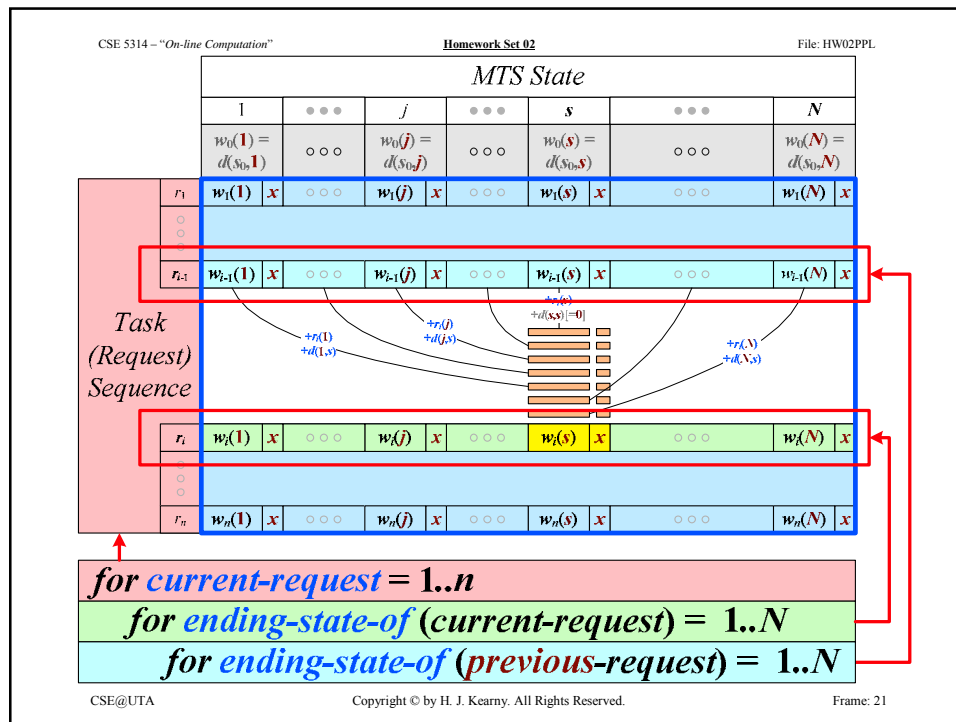
$$aN^2 + bN$$

	NOT <i>Metric-Space</i>	IS <i>Metric-Space</i>
Actual	$1 \cdot N^2 + (2n + T) N$	$\frac{1}{2} N^2 + (2n + T + 1) N$
Limit _{T=N}	Actual + (N-T)N	Actual + (N-T)N

Computation: Load TTPC & ITC

- Both items part of problem specification.
- Computation per se composed solely of “loading”, prior to subsequent look-up use.
- Thus, expression for time complexity equivalent to that for storage requirement:
- TTPC: $T \cdot N (\leq N^2)$
- ITC: *Not metric* – $N \cdot N$
Metric – $\left(\frac{N}{2} + 1\right) N$

Computation: Offline-WFA-DP Table



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Computation: Offline-WFA-DP Table

- All three loops must be completely passed (no shortcuts).
- Computation time:

$nNN = nN^2$

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Computation: Optimal Cost & Schedule

- Optimal cost of serving entire sequence is value of minimal entry in final row of DP table.
- Computation time is time to pass final row:

N

Offline-computation DP Table for MTS

		MTS State							
		0	1	2	3	...	s	...	N
Task Sequence σ and Prefixes σ_i	σ_0		$w_0(1)$	$w_0(2)$	$w_0(3)$	•	$w_0(s)$	•	$w_0(N)$
	σ_1	r_1	$w_1(1)$	$w_1(2)$	$w_1(3)$	•	$w_1(s)$	•	$w_1(N)$
	σ_2	r_2	$w_2(1)$	$w_2(2)$	$w_2(3)$	•	$w_2(s)$	•	$w_2(N)$
	σ_3	r_3	$w_3(1)$	$w_3(2)$	$w_3(3)$	•	$w_3(s)$	•	$w_3(N)$
	•	•	•	•	•	•	•	•	•
	•	•	•	•	•	•	•	•	•
	σ_i	r_i	$w_i(1)$	$w_i(2)$	$w_i(3)$	•	$w_i(s)$	•	$w_i(N)$
	•	•	•	•	•	•	•	•	•
	•	•	•	•	•	•	•	•	•
	σ_n	r_n	$w_n(1)$	$w_n(2)$	$w_n(3)$	•	$w_n(s)$	•	$w_n(N)$

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Computation: Optimal Cost & Schedule

- Schedule of service and other desired intermediate results extracted from recursive traceback through DP table.
- Ancillary activities (e.g., constructing a secondary “results” structure for some need) are ignored.
- Computation time is time to pass back to a single entry in all rows:

n

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Offline-computation DP Table for MTS

Task Sequence σ and Prefixes σ_i

		MTS State						
		1	2	3	...	s	...	N
σ_0 σ_1 σ_2 σ_3 \vdots σ_i \vdots σ_n	0	$w_0(1)$	$w_0(2)$	$w_0(3)$...	$w_0(s)$...	$w_0(N)$
	r_1	$w_1(1) _?$	$w_1(2) _?$	$w_1(3) _?$...	$w_1(s) _?$...	$w_1(N) _?$
	r_2	$w_2(1) _?$	$w_2(2) _?$	$w_2(3) _?$...	$w_2(s) _?$...	$w_2(N) _?$
	r_3	$w_3(1) _?$	$w_3(2) _?$	$w_3(3) _?$...	$w_3(s) _?$...	$w_3(N) _?$
	\vdots							
	σ_i	$w_i(1) _?$	$w_i(2) _?$	$w_i(3) _?$...	$w_i(s) _?$...	$w_i(N) _?$
	\vdots							
	σ_n	$w_n(1) _?$	$w_n(2) _?$	$w_n(3) _?$...	$w_n(s) _?$...	$w_n(N) _?$

	r_1	r_2	r_3	...	r_i	...	r_n
Processed in:	Start in s_0	a	b	c	x		
then MOVED & ENDED in:	u	b	c		S_i		S_{n-1} S_n

Request Service Cost	(-)	(-)	(-)	(-)	(-)	(-)	(-)
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$w_i(s_i)$

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Toward Total Computation Time

- Startup loading - TTPC: $T \cdot N (\leq N^2)$
- Startup loading - ITC:
 - Not metric* – $N \cdot N$
 - Metric* – $\left(\frac{N}{2} + 1\right)N$
- Offline-WFA-DP Computation: nN^2
- Find optimal cost: N
- Trace-back for service schedule: n

Toward Total Computation Time

For a space that is NOT metric:

$$\begin{aligned} \textit{Actual} &= TN + N^2 + nN^2 + N + n \\ &= (n + 1)N^2 + (1 + T)N + n \end{aligned}$$

$$\begin{aligned} \textit{Limit}_{T=N} &= N^2 + N^2 + nN^2 + N + n \\ &= (n + 1 + 1)N^2 + (1)N + n \\ &= \textit{Actual} + (N - T)N \end{aligned}$$

Toward Total Computation Time

For a metric space:

$$\text{Actual} = TN + \left(\frac{N}{2} + 1\right)N + nN^2 + N + n$$

$$= TN + \frac{N^2}{2} + N + nN^2 + N + n$$

$$= \left(n + \frac{1}{2}\right)N^2 + (T + 2)N + n$$

$$\text{Limit}_{T=N} = N^2 + \frac{N^2}{2} + N + nN^2 + N + n$$

$$= \left(n + \frac{1}{2} + 1\right)N^2 + (2)N + n$$

$$= \text{Actual} + (N - T)N$$

Storage & Time Recap

- In both storage & time:

$$\text{Limit}_{T=N} = \text{Actual} + (N - T)N$$

	<i>NOT Metric-Space</i>	<i>IS Metric-Space</i>
Actual Storage	$1 \cdot N^2 + (2n + T)N$	$\frac{1}{2}N^2 + (2n + T + 1)N$
Actual Time	$(n + 1)N^2 + (1 + T)N + n$	$\left(n + \frac{1}{2}\right)N^2 + (T + 2)N + n$

Perspective: Who dominates n or N ?

In a k -server example with k servers in a space of V vertices:

- May expect number of MTS states N to approximate number of combinations “ V choose k ” (if bar more than one server at a point):

$$N = \binom{V}{k} = \frac{V!}{k!(V-k)!}$$

Perspective: Who dominates n or N ?

- For metric space storage:

$$\begin{aligned} \text{Storage} &= \frac{1}{2} N^2 + (2n + T + 1)N \\ &= \text{FixedOverhead} + \text{DyamicCost} \\ &= \left[\frac{1}{2} N^2 + (T + 1)N \right] + \left[(2N)n \right] \end{aligned}$$

Perspective: Who dominates n or N ?

Assume modestly sized example:

- $V = 20$ points in a metric space
- $k = 5$ servers
- $T = 7$ types of request (different proc. costs)

For N MTS states:

$$\begin{aligned}
 N &= \left(\frac{V!}{k!(V-k)!} \right) = \frac{20!}{5!(20-5)!} = \frac{20!}{5!(15)!} \\
 &= \frac{16 \cdot 17 \cdot 18 \cdot 19 \cdot 20}{2 \cdot 3 \cdot 4 \cdot 5} = 16 \cdot 17 \cdot 3 \cdot 19 = 15,504
 \end{aligned}$$

Perspective: Who dominates n or N ?

How many storage locations are required:

Storage = FixedOverhead + DynamicCost

$$\begin{aligned}
 &= \left[\frac{1}{2} N^2 + (T+1)N \right] + \left[(2N)n \right] \\
 &= \left[\frac{1}{2} (15504)^2 + (7+1)(15504) \right] + \left[(2 \cdot 15504)n \right] \\
 &= (15504)[7760] + \left[(31008)n \right] \\
 &= 120,311,040 + (31008)n
 \end{aligned}$$

Perspective: Who dominates n or N ?

Space if *sizeof*(storage-location) = 4 bytes:

$$\text{StorageSpace} = \text{FixedOverheadSpace} + \text{DyamicCostSpace}$$

$$= 4 \cdot [120,311,040 + (31,008)n]$$

$$= 481,244,160 + (124,032)n$$

$$1Gb = 1,073,741,824$$

$$1,073,741,824 = 481,244,160 + 124,032n$$

$$n = \frac{1073741824 - 481244160}{124032}$$

$$= \frac{592,497,664}{124032} \sim 4,777 \text{ requests}$$

Perspective: Who dominates n or N ?

Assume our idiot box has 1 gig of memory. We should be able to whip out 4,777 requests pretty quickly....

Perspective: Who dominates n or N ?

Can determine number of time (calculation) units using number of storage units:

$$\text{Time} = \left(\frac{1}{2} + n \right) N^2 + (T + 2)N + n$$

$$\text{Storage} = \left(\frac{1}{2} \right) N^2 + (2n + T + 1)N$$

$$\text{Time} = \text{Storage} + \text{ConversionFactor}$$

$$= \text{Storage} + (nN^2 - 2nN + N + n)$$

Perspective: Who dominates n or N ?

$$\text{Time} = \text{Storage} + (nN^2 - 2nN + N + n)$$

$$= \text{Storage} + (nN^2 - (2n - 1)N + n)$$

$$= [120,311,040 + (31,008)n] + (n(15504)^2 - (2n - 1)(15504) + n)$$

$$= 120,311,040 + (31,008)n + n(15504)^2 - (2n - 1)(15504) + n$$

$$= 120,311,040 + (31,008)n + n(15504)^2 - 31008n + (15504) + n$$

$$= 120,311,040 + n(15504)^2 + (15504) + n$$

$$= 120,311,040 + n(240374016) + (15504) + n$$

$$= 120,326,544 + n(240,374,017)$$

$$= 120,326,544 + (4,777)(240,374,017)$$

$$= 120,326,544 + (4,777)(240,374,017)$$

$$= 1,148,387,005,753 \text{ calculation units}$$

Perspective: Who dominates n or N ?

If 1,000,000 calculations occur per second,
this problem will only take:

13 seconds less than 13days + 7 hours

*Assuming, after squinting at the dim console
lights for a couple hours, you don't then
reboot figuring the machine's hung...*

(Parallel/distributed, anyone?)

*End of
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